## HD66503

## (240-Channel Common Driver with Internal LCD Timing Circuit)

## HITACHI

ADE-207-301(Z)
'99.9
Rev. 0.0

## Description

The HD66503 is a common driver for liquid crystal dot-matrix graphic display systems. This device incorporates a 240 liquid crystal driver and an oscillator, and generates timing signals (alternating signals and frame synchronizing signals) required for the liquid crystal display. It also achieves low current consumption of $100 \mu \mathrm{~A}$ through the CMOS process. Combined with the HD66520, a 160-channel column driver with an internal RAM, the HD66503 is optimal for use in displays for portable information tools.

## Features

- LCD timing generator: $1 / 120,1 / 240$ duty cycle internal generator
- Alternating signal waveform generator: Pin programmable 2 to 63 line inversion
- Recommended display duty cycle: $1 / 120,1 / 240$ (master mode): $1 / 120$ to $1 / 240$ (slave mode)
- Number of LCD driver: 240
- Power supply voltage: 2.7 to 5.5 V
- High voltage: 8 to $28-\mathrm{V}$ LCD drive voltage
- Low power consumption: $100 \mu \mathrm{~A}$ (during display)
- Internal display off function
- Oscillator circuit with standby function: 130 kHz (max)
- Display timing operation clock: 65 kHz (max) (operating at $1 / 2$ system clock)
- Package: 272-pin TCP
- CMOS process


## Ordering Information

| Type No. | TCP | Outer Lead Pitch $(\mu \mathrm{m})$ |
| :--- | :--- | :--- |
| HD66503TA0 | Straight TCP | 200 |
| HD66503TB0 | Folding TCP | 200 |

## Pin Arrangement



Note : This figure does not specify the tape carrier package dimensions.

## Pin Description

| Classification | Symbol | Pin No. | Pin Name | I/O | Number of Pins | Functions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply | $\begin{aligned} & \mathrm{V}_{\mathrm{CC1}}, \\ & \mathrm{~V}_{\mathrm{CC} 2} \end{aligned}$ | $\begin{aligned} & 246 \\ & 267 \end{aligned}$ | $\mathrm{V}_{\text {cc }}$ | Power supply | 2 | $\mathrm{V}_{\text {cc }}-\mathrm{GND}$ : logic power supply |
|  | GND | 250 | GND | Power supply | 1 |  |
|  | $\begin{aligned} & \overline{V_{\text {EEL }},} \\ & \mathrm{V}_{\text {EER }} \end{aligned}$ | $\begin{aligned} & 245 \\ & 268 \end{aligned}$ | $V_{\text {EE }}$ | Power supply | 2 | $\mathrm{V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}$ : LCD drive circuits power supply |
|  | V1L, R | $\begin{aligned} & 244 \\ & 269 \end{aligned}$ | V1 | Input | 2 | LCD drive level power supply See Figure 1. |
|  | V2L, R | $\begin{aligned} & 241 \\ & 272 \end{aligned}$ | V2 | Input | 2 |  |
|  | V5L, R | $\begin{aligned} & 242 \\ & 271 \end{aligned}$ | V5 | Input | 2 |  |
|  | V6L, R | $\begin{aligned} & 243 \\ & 270 \end{aligned}$ | V6 | Input | 2 |  |
| Control signals | M/S | 266 | Master/slave | Input | 1 | Controls the initiation and termination of the LCD timing generator. In addition, the input/output is determined of 4 signal pins: display data transfer clock (CL1); first line marker (FLM); alternating signal (M); and display off control ( $\overline{\mathrm{DOC}}$ ). See Table 1 for details. |
|  | DUTY | 259 | Duty | Input | 1 | Selects the display duty cycle. Low level: $1 / 120$ display duty ratio High level: $1 / 240$ display duty ratio |
|  | MWSO to MWS5 | $\begin{aligned} & 257 \\ & 256 \\ & 255 \\ & 254 \\ & 253 \\ & 252 \end{aligned}$ | MWSO <br> MWS1 <br> MWS2 <br> MWS3 <br> MWS4 <br> MWS5 | Input | 6 | The number of line in the line alternating waveform is set during master mode. <br> The number of lines can be set between 10 and 63 . <br> When using the external alternating signal or during slave mode, set the number of lines to 0 . See Table 2. |
|  | MEOR | 258 | M ExclusiveOR | Input | 1 | During master mode, the signals alternating waveform output from pin M is selected. <br> During low level, the line alternating waveform is output from pin M. During high level, pin M outputs an EOR (exclusive OR) waveform between a line alternating waveform and frame alternating waveform. Set the pin to low during slave mode. See Table 3. |


| Classification | Symbol | Pin No. | Pin Name | I/O | Number of Pins | Functions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control signals | CR, R, C | $\begin{aligned} & \hline 247 \\ & 248 \\ & 249 \end{aligned}$ | $\begin{aligned} & \hline \mathrm{CR} \\ & \mathrm{R} \\ & \mathrm{C} \end{aligned}$ |  | 3 | These pins are used as shown in Figure 4 in master mode, and as shown in Figure 5 in slave mode. |
|  | $\overline{\text { RESET }}$ | 261 | Reset | Input | 1 | The following initiation will be proceeded by setting to initiation. <br> 1) Stops the internal oscillator or the external oscillator clock input. <br> 2) Initializes the counters of the liquid crystal display timing generator and alternating signal $(\mathrm{M})$ generator. <br> 3) Set display off control output ( $\overline{\mathrm{DOC}}$ ) to low and turns off display. <br> After reset, display off control output ( $\overline{\mathrm{DOC}}$ ) will stay low for four more frame cycles (four clocks of FLM signals) to prevent error display at initiation. The electrical characteristics are shown in Table 4. See Figure 2. <br> However, when reset is performed during operation, RAM data in the HD66520 which is used together with the HD66503 may be destroyed. Therefore, write data to the RAM again. |
| LCD timing | CL1 | 263 | Clock 1 | I/O | 1 | The bidirectional shift register shifts data at the falling edge of CL1. During master mode, this pin-outputs a data transfer clock with a two times larger cycle than the internal oscillator (or the cycle of the external clock) with a duty of $50 \%$. During slave mode, this pin inputs the external data transfer clock. |
|  | FLM | 264 | First line marker | I/O | 1 | During master mode, pin FLM outputs the first line marker. During slave mode, this pin inputs the external data first line marker. The shift direction of the first line marker is determined by DUTY and SHL signal as follows. Set signal DUTY to high during slave mode. See Table 5. |
|  | M | 262 | M | I/O | 1 | Pin M inputs and outputs the alternating signal of the LCD output. |


| Classi- <br> fication | Symbol | Pin No. | Pin Name | I/O | Number <br> of Pins | Functions |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Note: 30 input/outputs (excluding driver block)


Figure 1 LCD Drive Levels


Figure 2 Reset Pin Operation


Figure 3 LCD Drive Output

## Table 1 M/ $\overline{\mathbf{S}}$ Signal Status

| $\mathbf{M} / \overline{\mathbf{S}}$ | Mode | LCD Timing Generator | CL1, FLM, M, $\overline{\text { DOC }}$ Input/Output State |
| :--- | :--- | :--- | :--- |
| H | Master | $1 / 120$ or $1 / 240$ duty cycle control | Output |
| L | Slave | Stop | Input |

Table 2 MSW0 to MSW5 Signals Status

| Number of Lines | MWS5 | MWS4 | MWS3 | MWS2 | MWS1 | MWS0 | Line Alternating Waveform | Pin M State |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | - | Input |
| 1 | 0 | 0 | 0 | 0 | 0 | 1 | Disable | Output |
| 2 | 0 | 0 | 0 | 0 | 1 | 0 | 2-line alternation |  |
| 3 to 63 | 0 to 1 | 0 to 1 | 0 to 1 | 0 to 1 | 1 to 1 | 1 to 1 | 3 -line alternation to 63 -line alternation |  |

Table 3 MEOR Signal Status

| Mode | MEOR | Types of Alternating Waveforms Output by Pin M |
| :--- | :--- | :--- |
| Master | H | Line alternating waveform $\oplus$ frame alternating waveform |
|  | L | Line alternating waveform |
| Slave | L | - |

Table 4 Power Supply Conditions

| Item | Symbol | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Reset time | $\mathrm{t}_{\text {reset }}$ | 1.0 | - | - | $\mu \mathrm{s}$ |
| Rise time | $\mathrm{t}_{\mathrm{r}}$ | - | - | 200 | ns |

Table 5 FLM Status Control

| Mode | DUTY | SHL | Shift Direction of First Line Marker |
| :--- | :--- | :--- | :--- |
| Master | H | H | X240 $\rightarrow$ X1 |
|  |  | L | X1 $\rightarrow$ X240 |
|  | L | H | X120 $\rightarrow$ X1, X240 $\rightarrow$ X121 |
| Slave | H | H | X1 $\rightarrow$ X120, X121 $\rightarrow$ X240 |
|  |  | L $240 \rightarrow$ X1 |  |

## Internal Block Diagram



1. CR Oscillator: The CR oscillator generates the HD66503 operation clock. During master mode, since the operation clock is needed, connect oscillation resistor $R_{f}$ with oscillation capacitor $C_{f}$ as follows. When the external clock is used, input external clock to pin CR and open pins C and R (Figure 4).

When using the HD66503 during slave mode, the operation clock will not be needed; therefore, connect pin CR to $\mathrm{V}_{\mathrm{CC}}$ and open pins C and R (Figure 5).
2. Liquid Crystal Timing Generator: The liquid crystal timing generator creates various signals for the LCD. During master mode $\left(\mathrm{M} / \overline{\mathrm{S}}=\mathrm{V}_{\mathrm{CC}}\right)$, the generator operates the HD66503's internal circuitry as a common internal driver using the generated LCD signals. In addition, signals CL1, M, and $\overline{\mathrm{DOC}}$ created by this generator can synchronously display data on a liquid crystal display by inputting them into the RAMprovided segment driver HD66520 used together with HD66503. During slave mode (M/ $\overline{\mathrm{S}}=\mathrm{GND}$ ), this generator stops; the slave HD66503 operates based on signals CL1, M, $\overline{\text { DOC }}$, and FLM generated by the master HD66503.
3. $\mathbf{M} / \overline{\mathbf{S}}$ Switcher: Controls the input and output of LCD signals CL1, FLM, M, and $\overline{\mathrm{DOC}}$.

This circuit outputs data when $M / \bar{S}=V_{C C}$ (master mode) and inputs data when $M / \bar{S}=$ GND (slave mode).
4. Alternating Signal Generator: Generates the alternating signal for the liquid crystal display. Since the alternating signal decreases cross talk, it can alternate among 2 to 63 lines. The number of lines are specified with pins MWS0 to MWS5 is set to either $\mathrm{V}_{\mathrm{CC}}$ or GND.

Moreover, the alternating signal can be externally input by grounding pins MWS0 to MWS5. In this case, the alternating signal is input from $\operatorname{pin} \mathrm{M}$.


Figure 4 Oscillator Connection in Master Mode


Figure 5 Oscillator Connection in Slave Mode
5. Display Off Control Circuit: Controls display-off function by using external display off signal $\overline{\mathrm{DISPS}}$ and automatic display off signal FLMM generated by the liquid crystal timing generator. Automatic display off signal FLMM is an internal signal that is used to turn off the display in four frames after signal reset is released. As a result, it is possible to turn off display using the display off signal that is sent randomly from an external LSI and automatically prevent incorrect display after reset release.
6. Bidirectional Shift Register: This is a 240 -bit bidirectional shift register. This register can change the shift direction using signal SHL. During master mode, the scan signal of the common driver can be generated by sequentially shifting first line marker signal FLM generated internally. During slave mode, a scan signal is generated by sequentially shifting first line marker signal FLM input from pin FLM.
7. Level Shifter: Boosts the logic signal to a high voltage signal for the LCD.
8. LCD Drive Circuit: One of the LCD levels V1, V2, V5, and V6 are selected and output via pin X according to the combination of the data in the bidirectional shift register and signal M .

Table 6 Output Level of LCD Circuit

| Data in the Shift Register | M | Output Level |
| :--- | :--- | :--- |
| 1 | 1 | V2 |
| 0 | 1 | V6 |
| 1 | 0 | V1 |
| 0 | 0 | V5 |

## Internal Function Description

1. Generation of Signals CL1 and FLM: Signal CL1 shifts the scanning signal of the common driver. It is a $50 \%$ duty-ratio clock that changes level synchronously with the rising edge of oscillator clock CR.

FLM is a clock signal that is output once every 240 CL1 clock cycles for a duty of $1 / 240\left(\mathrm{DUTY}=\mathrm{V}_{\mathrm{CC}}\right)$, and every 120 CL1 clock cycles for a duty of $1 / 120$ (DUTY = GND).
2. Generation of Signal M: Signal M alternates current in the LCD. It alternates the current to decrease cross talk after a certain number of lines ranging from 2 to 63 lines. The number of lines can be specified with pins MWS0 to MWS5 by setting each pin to either $\mathrm{V}_{\mathrm{CC}}$ or GND ( H or L ). In addition, when pin MEOR is connected to GND, signal M is a simple line alternating waveform, and when pin MEOR is connected to $\mathrm{V}_{\mathrm{CC}}$, signal M is an EOR (exclusive OR ) of line alternating waveform and frame alternating waveform.


Figure 6 Generation of Signals CL1 and FLM


Figure 7 Generation of Signal M
3. Auto Display-Off Control: This functions prevents incorrect display after reset release. The display is turned off four frames following after reset release. In addition, the display off control signal shown in Figure 8 is output by pin $\overline{\text { DOC. This pin is connected to pin } \overline{\text { DISPOFF }} \text { of the HD66520. }}$


Figure 8 Automatic Display-Off Control Function

## Application Example

## Outline of HD66503 System Configuration

The HD66503 system configuration is outlined in Figures 9 and 10. Refer to the connection list (Table 7) for connection details.

- When a single HD66503 is used to configure a small display (Figure 9)
- When two HD66503s are used to configure a large display (Figure 10)


Figure 9 When Using a Single HD66503


Figure 10 When Using Two HD66503s

## HD66503 Connection List

Table 7 HD66503 Connection List

| Connection Example | M/S | DUTY | MWSO, MWS1, MWS2, MWS3, MWS4, MWS5 | MEOR | RESET | DISPOFF | CR | R | C | CL1 | FLM | M | $\overline{\text { DOC }}$ | SHL | X1 to X240 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | H | H | Sets the number of lines for alternating the current | H | From CPU or external reset circuit | $\begin{aligned} & \text { From } \\ & \text { controller } \end{aligned}$ | $\mathrm{R}_{\mathrm{f}}$ | R |  | $\begin{aligned} & \hline \text { To CL1 of } \\ & \text { HD66520 } \end{aligned}$ | To FLM ofHD66520 | To M of HD66520 | To DISPOFF of HD66520 | L | COM1 to COM240 |
|  |  |  |  |  |  |  | $\mathrm{C}_{\mathrm{f}}$ |  | $\mathrm{Cf}_{f}$ |  |  |  |  | H | COM240 to COM1 |
| B | H | H | Sets the number of lines for alternating the current | H | From CPU or external reset circuit | From controller | $\mathrm{R}_{\mathrm{f}}$ | $\mathrm{R}_{\mathrm{f}}$ |  | To CL1 of HD66520 HD66503 | To FLM of HD66520 HD66503 | To M of HD66520 HD66503 | To $\overline{\mathrm{DOC}}$ of HD66503 <br> T0 DISPOFF of HD66520 | L | COM1 to COM240 |
|  |  |  |  |  |  |  | $\mathrm{C}_{\text {f }}$ |  | $\mathrm{C}_{\text {f }}$ |  |  |  |  | H | COM240 to COM1 |
| C | L | H | Sets the number of lines for alternating the current | L | From CPU or external reset circuit | H | H | - | - | $\begin{aligned} & \text { From CL1 } \\ & \text { of HD66503 } \end{aligned}$ | From FLM of HD66503 | From M of HD66503 | From $\overline{\text { DOC }}$ of HD66503 | L | COM241 to COM480 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | H | COM480 to COM241 |
| D | H | H | Sets the number of lines for alternating the current | H | From CPU or external reset circuit | From controller | From external oscillato | - | - | To CL1 of HD66520 | To FLM of HD66520 | To M of HD66520 | $\begin{aligned} & \text { To } \overline{\text { DISPOFF }} \\ & \text { of HD66520 } \end{aligned}$ | L | COM1 to COM240 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | H | COM240 to COM1 |
| E | H | H | Sets the number of lines for alternating the current | H | From CPU or external reset circuit | From controller | From external oscillator | - | - | To CL1 of HD66520 HD66503 | To FLM of HD66520 HD66503 | To M of HD66520 HD66503 | To $\overline{\mathrm{DOC}}$ of HD66503 | L | COM1 to COM240 |
|  |  |  |  |  |  |  |  |  |  |  |  |  | To DISPOFF of HD66520 | H | COM240 to COM1 |

= GND (Fixed)
$\mathrm{R}_{\mathrm{f}}$ : Oscillation resistor

## Example of System Configuration (1)

Figure 11 shows a system configuration for a $240 \times 160$-dot LCD panel using segment driver HD66520 with internal bit-map RAM. All required functions can be prepared for liquid crystal display with just two chips except for liquid crystal display power supply circuit functions. Refer to Timing Chart (1) for details.


Figure 11 System Configuration (1)

## Example of System Configuration (2)

Figure 12 shows a system configuration for a $240 \times 320$-dot LCD panel using segment driver HD66520 with internal bit-map RAM. Refer to Timing Chart (1) for details.


Figure 12 System Configuration (2)

Timing Chart (1)

|  |  | 5 8 8 |  | \% | ¢ ${ }_{8}^{8}$ | (1) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Figure 13 Timing Chart (1)

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## Example of System Configuration (3)

Figure 14 shows a system configuration for a $320 \times 480$-dot LCD panel using segment driver HD66520 with internal bit-map RAM. Refer to Timing Chart (2) for details.


Figure 14 System Configuration (3)

Timing Chart (2)


Figure 15 Timing Chart (2)

## Power Supply Circuit



Note: The values of R1 and R2 vary with the LCD panel used. When the bias factor is $1 / 15$, for example, the values of R1 and R2 can be determined as follows:

$$
\begin{gathered}
\frac{R 1}{4 R 1+R 2}=\frac{1}{15} \\
\text { If } \mathrm{R} 1=3 \mathrm{k} \Omega \text {, then } \mathrm{R} 2=33 \mathrm{k} \Omega
\end{gathered}
$$

Figure 16 Power Supply Circuit

## Absolute Maximum Ratings

| Item | Symbol | Ratings | Unit | Notes |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Power voltage | Logic circuit | $\mathrm{V}_{\mathrm{CC}}$ | -0.3 to +7.0 | V | 2 |
|  | LCD drive circuit | $\mathrm{V}_{\mathrm{EE}}$ | $\mathrm{V}_{\mathrm{CC}}-30.0$ to $\mathrm{V}_{\mathrm{CC}}+0.3$ | V | 5 |
| Input voltage (1) |  | VT 1 | -0.3 to $\mathrm{V}_{\mathrm{CC}}+0.3$ | V | 2,3 |
| Input voltage (2) | VT 2 | $\mathrm{~V}_{\mathrm{EE}}-0.3$ to $\mathrm{V}_{\mathrm{cC}}+0.3$ | V | 4,5 |  |
| Operating temperature | $\mathrm{T}_{\text {opr }}$ | -30 to +75 | ${ }^{\circ} \mathrm{C}$ |  |  |
| Storage temperature | $\mathrm{T}_{\mathrm{stg}}$ | -55 to +110 | ${ }^{\circ} \mathrm{C}$ |  |  |

Notes: 1. If the LSI is used beyond its absolute maximum rating, it may be permanently damaged. It should always be used within the limits of its electrical characteristics in order to prevent malfunction or unreliability.
2. Measured relative to GND ( 0 V ).
3. Applies to all input pins except for V1L, V1R, V2L, V2R, V5L, V5R, V6L, and V6R, and to input/output pins in high-impedance state.
4. Applies to pins V1L, V1R, V2L, V2R, V5L, V5R, V6L, and V6R.
5. Apply the same voltage to pairs V1L and V1R, V2L and V2R, V5L and V5R, V6L and V6R, and $V_{\text {EEL }}$ and $V_{\text {EER }}$.
It is important to preserve the relationships $\mathrm{V}_{\mathrm{CC} 1}=\mathrm{V}_{\mathrm{cC} 2} \geq \mathrm{V} 1 \mathrm{~L}=\mathrm{V} 1 \mathrm{R} \geq \mathrm{V} 6 \mathrm{~L}=\mathrm{V} 6 \mathrm{R} \geq \mathrm{V} 5 \mathrm{~L}=\mathrm{V} 5 \mathrm{R} \geq$ $\mathrm{V} 2 \mathrm{~L}=\mathrm{V} 2 \mathrm{R} \geq \mathrm{V}_{\mathrm{EEL}}=\mathrm{V}_{\mathrm{EER}}$

## HD66503

## Electrical Characteristics

DC Characteristics ( $\mathrm{V}_{\mathrm{CC}}=2.7$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=8$ to $28 \mathrm{~V}, \mathrm{GND}=0 \mathrm{~V}, \mathrm{Ta}=-\mathbf{3 0}$ to $+75^{\circ} \mathrm{C}$ )

| Item | Symbol | Min | Typ | Max | Unit | Measurement Condition | Notes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input high level voltage | VIH | $0.8 \mathrm{~V}_{\text {cc }}$ | - | $\mathrm{V}_{\text {cc }}$ | V |  | 1 |
| Input low level voltage | VIL | 0 | - | $0.2 \mathrm{~V}_{\text {cc }}$ | V |  | 1 |
| Output high level voltage | VOH | $\mathrm{V}_{\mathrm{cc}}-0.4$ | - | - | V | $\mathrm{I}_{\mathrm{OH}}=-0.4 \mathrm{~mA}$ | 2 |
| Output low level voltage | VOL | - | - | 0.4 | V | $\mathrm{I}_{\mathrm{oL}}=+0.4 \mathrm{~mA}$ | 2 |
| Driver "on" resistance | $\mathrm{R}_{\text {on }}$ | - | - | 2.0 | $\mathrm{k} \Omega$ | $\begin{aligned} & \mathrm{V}_{C C}-\mathrm{V}_{\mathrm{VE}}=28 \mathrm{~V}, \\ & \text { load current: } \pm 150 \mu \mathrm{~A} \end{aligned}$ | 13, 14 |
| Input leakage current (1) | $\mathrm{I}_{11}$ | -1.0 | - | 1.0 | $\mu \mathrm{A}$ | $\mathrm{VIN}=0$ to $\mathrm{V}_{\mathrm{cc}}$ | 1 |
| Input leakage current (2) | $\mathrm{I}_{\mathrm{LL} 2}$ | -25 | - | 25 | $\mu \mathrm{A}$ | $\mathrm{VIN}=\mathrm{V}_{\text {EE }}$ to $\mathrm{V}_{\text {CC }}$ | 3 |
| Operating frequency | $\mathrm{f}_{\text {opr1 }}$ | 10 | - | 200 | kHz | Master mode (external clock operation) | 4 |
| Operating frequency (2) | $\mathrm{f}_{\text {opr2 }}$ | 5 | - | 500 | kHz | Slave mode | 5 |
| Oscillation frequency (1) | $\mathrm{f}_{\text {osc } 1}$ | 70 | 100 | 130 | kHz | $\begin{aligned} & \mathrm{C}_{\mathrm{f}}=100 \mathrm{pF} \pm 5 \%, \\ & \mathrm{R}_{\mathrm{f}}=51 \mathrm{k} \Omega \pm 2 \%, \end{aligned}$ | 6, 12 |
| Oscillation frequency (2) | $\mathrm{f}_{\text {osc } 2}$ | 21 | 30 | 39 | kHz | $\begin{aligned} & \mathrm{C}_{\mathrm{f}}=100 \mathrm{pF} \pm 5 \%, \\ & \mathrm{R}_{\mathrm{f}}=180 \mathrm{k} \Omega \pm 2 \% \end{aligned}$ | 6, 12 |
| Power consumption (1) | $\mathrm{I}_{\text {GND } 1}$ | - | - | 80 | $\mu \mathrm{A}$ | Master mode <br> 1/240 duty cycle, $\begin{aligned} & \mathrm{C}_{\mathrm{f}}=100 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{f}}=180 \mathrm{k} \Omega \\ & \mathrm{~V}_{\mathrm{CC}}-\mathrm{GND}=3 \mathrm{~V}, \\ & \mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=28 \mathrm{~V}, \end{aligned}$ | 7, 8 |
| Power consumption (2) | $\mathrm{I}_{\text {GND } 2}$ | - | - | 20 | $\mu \mathrm{A}$ | Master mode <br> $1 / 240$ duty cycle external clock $\begin{aligned} & \mathrm{f}_{\text {orr }}=30 \mathrm{kHz} \\ & \mathrm{~V}_{\text {CC }}-\mathrm{GND}=3 \mathrm{~V}, \\ & \mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=28 \mathrm{~V} \end{aligned}$ | 7,9 |
| Power consumption (3) | $\mathrm{I}_{\text {GND } 3}$ | - | - | 10 | $\mu \mathrm{A}$ | Slave mode 1/240 duty cycle during operation $\mathrm{f}_{\mathrm{CL}}=15 \mathrm{kHz}$ $\mathrm{V}_{\mathrm{cc}}^{\mathrm{L}}-\mathrm{GND}=3 \mathrm{~V},$ $\mathrm{V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=28 \mathrm{~V}$ | 7, 10 |

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|  |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Item | Symbol | Min | Typ | Max | Unit | Measurement <br> Condition | Notes |
| Power | $\mathrm{I}_{\mathrm{EE}}$ | - | - | 20 | $\mu \mathrm{~A}$ | Master mode <br> consumption |  |
|  |  |  |  |  | $1 / 240$ duty cycle, | 7,11 |  |
|  |  |  |  |  | $\mathrm{C}_{\mathrm{f}}=100 \mathrm{pF}$, |  |  |
|  |  |  | $\mathrm{R}_{\mathrm{f}}=180 \mathrm{k} \Omega$ |  |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}-\mathrm{GND}=3 \mathrm{~V}$ |  |  |  |  |  |
|  |  |  | $\mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=28 \mathrm{~V}$, |  |  |  |  |

Notes: 1. Applies to input pins MEOR, MWS0 to MWS5, DUTY, SHL, $\overline{\text { DISPOFF, M/ } \overline{\mathrm{S}}, \overline{R E S E T} \text {, and CR, }}$ and when inputting to input/output pins CL1, FLM, $\overline{\mathrm{DOC}}$, and M .
2. Applies when outputting from input/output pins CL1, FLM, $\overline{\mathrm{DOC}}$, and M.
3. Applies to V1L/R, V2L/R, V5L/R, and V6L/R. X1 to X240 are open.
4. Figure 17 shows the external clock specifications:


Figure 17 External Clock
5. Regulates to operation frequency limits of the bidirectional shift register in the slavemode.
6. Connect resistance Rf and capacitance Cf as follows:


Figure 18 Timing Components
7. Input and output currents are excluded. When a CMOS input is floating, excess current flows from the power supply through to the input circuit. To avoid this, VIH and VIL must be held to $\mathrm{V}_{\text {cc }}$ and GND levels, respectively.
8. This value is specified for the current flowing through GND under the following conditions: Internal oscillation circuit is used. Each terminal of MEOR, MWSO to MWS5, DUTY, SHL, $\overline{\mathrm{DISPOFF}}, \mathrm{M} / \overline{\mathrm{S}}$, and $\overline{\mathrm{RESET}}$ is connected to $\mathrm{V}_{\mathrm{cc}}$. Oscillator is set as described in note 6.
9. This value is specified for the current flowing through GND under the following conditions: Each terminal of MEOR, MWS0 to MWS5, DUTY, SHL, DISPOFF, M/S, and RESET is connected to $\mathrm{V}_{\mathrm{cc}}$. Oscillator is set as described in note 4.
10. This value is specified for the current flowing through GND under the following conditions: Each terminal of MEOR, MWS0 to MWS5, DUTY, SHL, DOC, DISPOFF, $\overline{\text { RESET, and CR is }}$ connected to $\mathrm{V}_{\mathrm{C}}$, $\mathrm{M} / \overline{\mathrm{S}}$ to GND , and frequency of CL1, FLM, M is respectively established as follows.

$$
\mathrm{f}_{\mathrm{CL} 1}=15 \mathrm{kHz}, \mathrm{f}_{\mathrm{FLM}}=62.5 \mathrm{~Hz}, \mathrm{f}_{\mathrm{M}}=120 \mathrm{~Hz}
$$

11. This value is specified for the current flowing through $\mathrm{V}_{\mathrm{EE}}$ under the following condition described in note 8. Do not connect any lines to pin X .
12. Figure 19 shows a typical relation among ocsillation frequency $R_{f}$ and $C_{f}$. Oscillation frequency may vary with mounting conditions.


Figure 19 Ocsillation Frequency Characteristics
13. Indicates the resistance between one pin from X 1 to X 240 and another pin from the V pins $\mathrm{V} 1 \mathrm{~L} / \mathrm{R}, \mathrm{V} 2 \mathrm{~L} / \mathrm{R}$, $\mathrm{V} 5 \mathrm{~L} / \mathrm{R}$, and $\mathrm{V} 6 \mathrm{~L} / \mathrm{R}$, when a load current is applied to the X pin; defined under the following conditions:

$$
\begin{aligned}
& V_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=28(\mathrm{~V}) \\
& \mathrm{V} 1 \mathrm{~L} / \mathrm{V}, \mathrm{~V} 6 \mathrm{~L} / \mathrm{R}=\mathrm{V}_{\mathrm{CC}}-1 / 10\left(\mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}\right) \\
& \mathrm{V} 5 \mathrm{~L} / \mathrm{R}, \mathrm{~V} 2 \mathrm{~L} / \mathrm{R}=\mathrm{V}_{\mathrm{EE}}+1 / 10\left(\mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}\right)
\end{aligned}
$$



Figure 20 On Resistance Conditions
14. V1L/R and V6L/R should be near the $\mathrm{V}_{\mathrm{Cc}}$ level, and $\mathrm{V} 5 \mathrm{~L} / \mathrm{R}$ and $\mathrm{V} 2 \mathrm{~L} / \mathrm{R}$ should be near the $\mathrm{V}_{\mathrm{EE}}$ level. All these voltage pairs should be separated by less than $\Delta \mathrm{V}$, which is the range within which $\mathrm{R}_{\mathrm{ON}}$, the LCD drive circuits' output impedance is stable. Note that $\Delta \mathrm{V}$ depend on power supply voltages $\mathrm{V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}$. See Figure 21 .


Figure 21 Relationship between Driver Output Waveform

AC Characteristics ( $\mathrm{V}_{\mathrm{CC}}=2.7$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}-\mathrm{V}_{\mathrm{EE}}=8$ to $28 \mathrm{~V}, \mathrm{GND}=\mathbf{0 V}, \mathrm{Ta}=\mathbf{- 3 0}$ to $+\mathbf{7 5}{ }^{\circ} \mathrm{C}$ )

Slave Mode (M/ $\overline{\mathbf{S}}=\mathbf{G N D}$ )

| Item | Symbol | Min | Typ | Max | Unit | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| CL1 high-level width | $\mathrm{t}_{\mathrm{cwH}}$ | 500 | - | - | ns | 1 |
| CL1 low-level width | $\mathrm{t}_{\mathrm{cWL}}$ | 500 | - | - | ns | 1 |
| FLM setup time | $\mathrm{t}_{\mathrm{Fs}}$ | 100 | - | - | ns | 1 |
| FLM hold time | $\mathrm{t}_{\mathrm{FH}}$ | 100 | - | - | ns | 1 |
| CL1 rise time | $\mathrm{t}_{\mathrm{r}}$ | - | - | 50 | ns | 1 |
| CL1 fall time | $\mathrm{t}_{\mathrm{f}}$ | - | - | 50 | ns | 1 |

Note: 1. Based on the load circuit shown in Figure 22.


Figure 22 Load Circuit


Figure 23 Slave Mode Timing

Master Mode (M/ $\overline{\mathbf{S}}=\mathbf{V}_{\text {CC }}$ )

| Item | Symbol | Min | Typ | Max | Unit | Notes |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| CL1 delay time | $\mathrm{t}_{\text {DCL1 }}$ | - | - | 1 | $\mu \mathrm{~s}$ |  |
| FLM delay time | $\mathrm{t}_{\text {DFLM }}$ | - | - | 1 | $\mu \mathrm{~s}$ |  |
| M delay time | $\mathrm{t}_{\text {DM }}$ | - | - | 500 | ns |  |
| FLM setup time | $\mathrm{t}_{\text {FS }}$ | $\mathrm{t}_{\text {osc }} / 2-500$ | - | - | ns |  |



Figure 24 Master Mode Timing

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